

MOTOROLA SEMICONDUCTOR TECHNICAL DATA

256K x 9 Bit Dynamic Random Access Memory Module

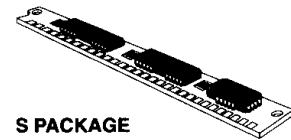
The MCM94256 is a 2.25M dynamic random access memory (DRAM) module organized as 262,144 x 9 bits. The module is a 30-lead single-in-line memory module (SIMM) consisting of two MCM514256A DRAMs housed in 20/26 J-lead small outline packages (SOJ) and one CMOS 256K x 1 DRAM housed in an 18-lead PLCC package, mounted on a substrate along with a 0.22 μ F (min) decoupling capacitor mounted adjacent to each DRAM. The MCM514256A is a 1.0 μ CMOS high-speed dynamic random access memory organized as 262,144 four-bit words and fabricated with CMOS silicon-gate process technology.

- Three-State Data Output
- Early-Write Common I/O Capability
- Fast Page Mode Capability
- TTL-Compatible Inputs and Outputs
- $\overline{\text{RAS}}$ -Only Refresh
- $\overline{\text{CAS}}$ Before $\overline{\text{RAS}}$ Refresh
- Hidden Refresh
- 512 Cycle Refresh:
MCM94256 = 8 ms (Max)
- Consists of Two 256K x 4 DRAMs, One 256K x 1 DRAM, and Three 0.22 μ F (Min) Decoupling Capacitors
- Unlatched Data Out at Cycle End Allows Two Dimensional Chip Selection
- Fast Access Time (t_{RAC}):
MCM94256-70 = 70 ns (Max)
MCM94256-80 = 80 ns (Max)
- Low Active Power Dissipation:
MCM94256-70 = 1.32 W (Max)
MCM94256-80 = 1.16 W (Max)
- Low Standby Power Dissipation:
TTL Levels = 33 mW (Max)
CMOS Levels = 16.5 mW (Max)
- $\overline{\text{CAS}}$ Control for Eight Common I/O Lines
- $\overline{\text{CAS}}$ Control for Separate I/O Pair

PIN NAMES

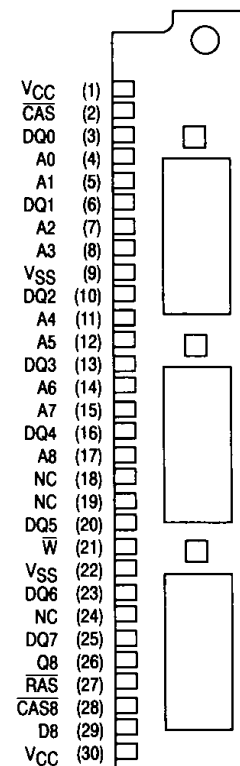
A0 – A8	Address Inputs
DQ0 – DQ7	Data Input/Output
D8	Data Input
Q8	Data Output
$\overline{\text{CAS}}$	Column Address Strobe
$\overline{\text{CAS8}}$	Column Address Strobe
$\overline{\text{RAS}}$	Row Address Strobe
$\overline{\text{W}}$	Read/Write Input
VCC	Power (+5 V)
VSS	Ground
NC	No Connection

MCM94256



**S PACKAGE
SIMM MODULE
CASE 839A-01**

TOP VIEW

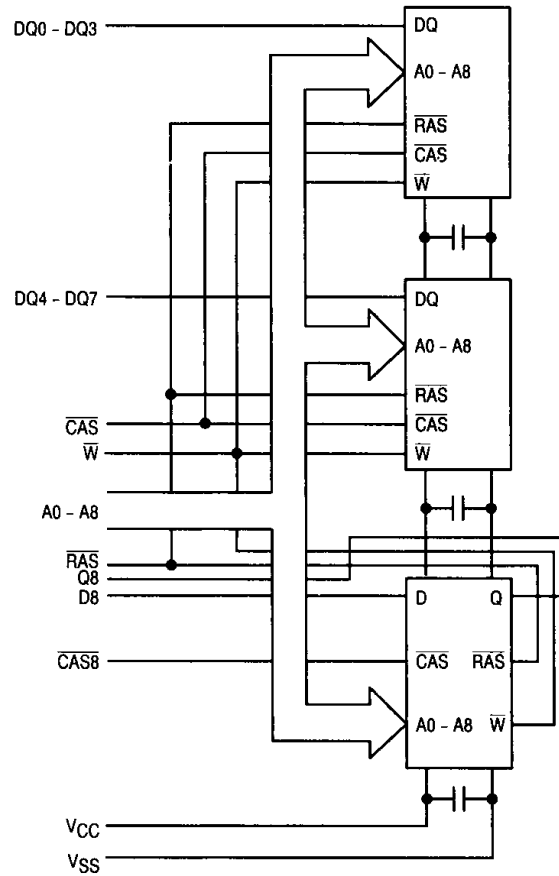


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FUNCTIONAL BLOCK DIAGRAM



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ABSOLUTE MAXIMUM RATINGS (See Note)

Rating	Symbol	Value	Unit
Power Supply Voltage	V_{CC}	-1 to +7	V
Voltage Relative to V_{SS} for Any Pin Except V_{CC}	V_{in}, V_{out}	-1 to +7	V
Data Out Current per DQ Pin	I_{out}	50	mA
Power Dissipation	P_D	1.8	W
Operating Temperature Range	T_A	0 to +70	°C
Storage Temperature Range	T_{stg}	-55 to +125	°C

NOTE: Permanent device damage may occur if ABSOLUTE MAXIMUM RATINGS are exceeded. Functional operation should be restricted to RECOMMENDED OPERATING CONDITIONS. Exposure to higher than recommended voltages for extended periods of time could affect device reliability.

This device contains circuitry to protect the inputs against damage due to high static voltages or electric fields; however, it is advised that normal precautions be taken to avoid application of any voltage higher than maximum rated voltages to this high-impedance circuit.

DC OPERATING CONDITIONS AND CHARACTERISTICS(V_{CC} = 5.0 V ± 10%, T_A = 0 to 70°C, Unless Otherwise Noted)**RECOMMENDED OPERATING CONDITIONS** (All voltages referenced to V_{SS})

Parameter	Symbol	Min	Typ	Max	Unit
Supply Voltage (Operating Voltage Range)	V _{CC}	4.5	5.0	5.5	V
	V _{SS}	0	0	0	
Logic High Voltage, All Inputs	V _{IH}	2.4	—	6.5	V
Logic Low Voltage, All Inputs	V _{IL}	-1.0	—	0.8	V

DC CHARACTERISTICS AND SUPPLY CURRENTS

Characteristic	Symbol	Min	Max	Unit	Notes
V _{CC} Power Supply Current MCM94256-70, t _{RC} = 130 ns MCM94256-80, t _{RC} = 150 ns	I _{CC1}	—	225 195	mA	1
V _{CC} Power Supply Current (Standby) ($\overline{RAS} = \overline{CAS} = V_{IH}$)	I _{CC2}	—	6	mA	
V _{CC} Power Supply Current During \overline{RAS} -Only Refresh Cycles MCM94256-70, t _{RC} = 130 ns MCM94256-80, t _{RC} = 150 ns	I _{CC3}	—	225 195	mA	1
V _{CC} Power Supply Current During Fast Page Mode Cycle MCM94256-70, t _{PC} = 40 ns MCM94256-80, t _{PC} = 45 ns	I _{CC4}	—	160 135	mA	1, 2
V _{CC} Power Supply Current (Standby) ($\overline{RAS} = \overline{CAS} = V_{CC} - 0.2$ V)	I _{CC5}	—	3	mA	
V _{CC} Power Supply Current During \overline{CAS} Before \overline{RAS} Refresh Cycle MCM94256-70, t _{RC} = 130 ns MCM94256-80, t _{RC} = 150 ns	I _{CC6}	—	225 195	mA	1
Input Leakage Current (V _{SS} ≤ V _{in} ≤ V _{CC})	I _{kg(I)}	-30	30	μA	
Output Leakage Current (\overline{CAS} at Logic 1, V _{SS} ≤ V _{out} ≤ V _{CC})	I _{kg(O)}	-10	10	μA	
Output High Voltage (I _{OH} = -5 mA)	V _{OH}	2.4	—	V	
Output Low Voltage (I _{OL} = 4.2 mA)	V _{OL}	—	0.4	V	

NOTES:

- Current is a function of cycle rate and output loading; maximum current is measured at the fastest cycle rate with the output open.
- Measured with one address transition per page mode cycle.

CAPACITANCE (f = 1.0 MHz, T_A = 25°C, V_{CC} = 5 V, Periodically Sampled Rather Than 100% Tested)

Parameter	Symbol	Max	Unit
Input Capacitance A0 - A8, \overline{W} , \overline{CAS} , \overline{RAS} D8, \overline{CAS}	C _{in}	30	pF
		17	
Input/Output Capacitance DQ0 - DQ7	C _{I/O}	17	pF
Output Capacitance Q8	C _{out}	17	pF

NOTE: Capacitance measured with a Boonton Meter or effective capacitance calculated from the equation: C = I ΔV/ΔV.

AC OPERATING CONDITIONS AND CHARACTERISTICS(V_{CC} = 5.0 V ± 10%, T_A = 0 to 70°C, Unless Otherwise Noted)**READ AND WRITE CYCLES** (See Notes 1, 2, 3, and 4)

Parameter	Symbol		MCM94256-70		MCM94256-80		Unit	Notes
	Standard	Alternate	Min	Max	Min	Max		
Random Read or Write Cycle Time	t _{RELREL}	t _{RC}	130	—	150	—	ns	5
Page Mode Cycle Time	t _{CELCEL}	t _{PC}	40	—	45	—	ns	
Access Time from $\overline{\text{RAS}}$	t _{RELQV}	t _{RAC}	—	70	—	80	ns	6, 7
Access Time from $\overline{\text{CAS}}$	t _{CELQV}	t _{CAC}	—	20	—	20	ns	6, 8
Access Time from Column Address	t _{AVQV}	t _{AA}	—	35	—	40	ns	6, 9
Access Time from Precharge $\overline{\text{CAS}}$	t _{CEHQV}	t _{CPA}	—	35	—	40	ns	6
$\overline{\text{CAS}}$ to Output in Low-Z	t _{CELOX}	t _{CLZ}	0	—	0	—	ns	6
Output Buffer and Turn-Off Delay	t _{CEHQZ}	t _{OFF}	0	20	0	20	ns	10
Transition Time (Rise and Fall)	t _T	t _T	3	50	3	50	ns	
$\overline{\text{RAS}}$ Precharge Time	t _{REHREL}	t _{RP}	50	—	60	—	ns	
$\overline{\text{RAS}}$ Pulse Width	t _{RELREH}	t _{RAS}	70	10,000	80	10,000	ns	
$\overline{\text{RAS}}$ Pulse Width (Fast Page Mode)	t _{RELREH}	t _{RASP}	70	100,000	80	100,000	ns	
$\overline{\text{RAS}}$ Hold Time	t _{CELREH}	t _{RSH}	20	—	20	—	ns	
$\overline{\text{CAS}}$ Hold Time	t _{RELCEH}	t _{CSH}	70	—	80	—	ns	
$\overline{\text{CAS}}$ Pulse Width	t _{CELCEH}	t _{CAS}	20	10,000	20	10,000	ns	
$\overline{\text{RAS}}$ to $\overline{\text{CAS}}$ Delay Time	t _{RELCEL}	t _{RCD}	20	50	20	60	ns	11
$\overline{\text{RAS}}$ to Column Address Delay Time	t _{RELAV}	t _{RAD}	15	35	15	40	ns	12
$\overline{\text{CAS}}$ to $\overline{\text{RAS}}$ Precharge Time	t _{CEHREL}	t _{CRP}	5	—	5	—	ns	
$\overline{\text{CAS}}$ Precharge Time (Page Mode Cycle Only)	t _{CEHCEL}	t _{CP}	10	—	10	—	ns	
Row Address Setup Time	t _{AVREL}	t _{ASR}	0	—	0	—	ns	
Row Address Hold Time	t _{RELAX}	t _{RAH}	10	—	10	—	ns	
Column Address Setup Time	t _{AVCEL}	t _{ASC}	0	—	0	—	ns	
Column Address Hold Time	t _{CELAX}	t _{CAH}	15	—	15	—	ns	
Column Address Hold Time Referenced to $\overline{\text{RAS}}$	t _{RELAX}	t _{AR}	55	—	60	—	ns	
Column Address to $\overline{\text{RAS}}$ Lead Time	t _{AVREH}	t _{RAL}	35	—	40	—	ns	
Read Command Setup Time	t _{WHCEL}	t _{RCS}	0	—	0	—	ns	

NOTES:

(continued)

- V_{IH} (min) and V_{IL} (max) are reference levels for measuring timing of input signals. Transition times are measured between V_{IH} and V_{IL}.
- An initial pause of 200 μs is required after power-up followed by 8 $\overline{\text{RAS}}$ cycles before proper device operation is guaranteed.
- The transition time specification applies for all input signals. In addition to meeting the transition rate specification, all input signals must transition between V_{IH} and V_{IL} (or between V_{IL} and V_{IH}) in a monotonic manner.
- AC measurements t_T = 5.0 ns.
- The specification for t_{RC} (min) is used only to indicate cycle time at which proper operation over the full temperature range (0°C ≤ T_A ≤ 70°C) is ensured.
- Measured with a current load equivalent to 2 TTL (− 200 μA, + 4 mA) loads and 100 pF with the data output trip points set at V_{OH} = 2.0 V and V_{OL} = 0.8 V.
- Assumes that t_{RCD} ≤ t_{RCD} (max).
- Assumes that t_{RCD} ≥ t_{RCD} (max).
- Assumes that t_{RAD} ≥ t_{RAD} (max).
- t_{OFF} (max) defines the time at which the output achieves the open circuit condition and is not referenced to output voltage levels.
- Operation within the t_{RCD} (max) limit ensures that t_{RAC} (max) can be met. t_{RCD} (max) is specified as a reference point only; if t_{RCD} is greater than the specified t_{RCD} (max) limit, then access time is controlled exclusively by t_{CAC}.
- Operation within the t_{RAD} (max) limit ensures that t_{RAC} (max) can be met. t_{RAD} (max) is specified as a reference point only; if t_{RAD} is greater than the specified t_{RAD} (max), then access time is controlled exclusively by t_{AA}.

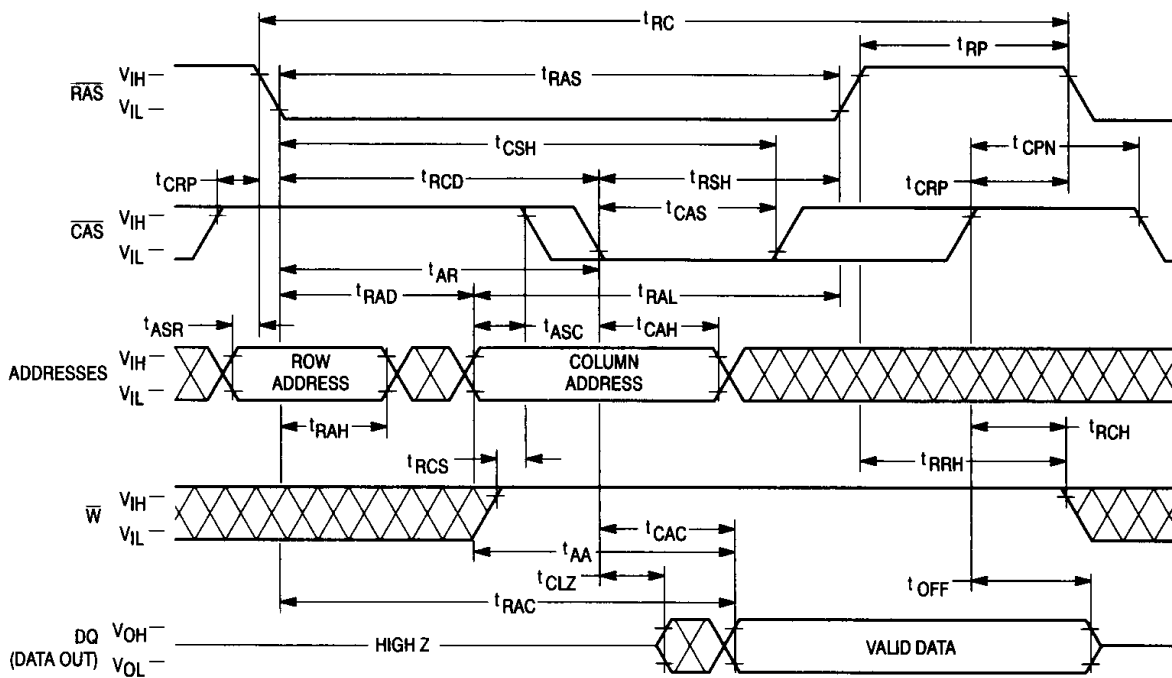
READ AND WRITE CYCLES (Continued)

Parameter	Symbol		MCM94256-70		MCM94256-80		Unit	Notes
	Standard	Alternate	Min	Max	Min	Max		
Read Command Hold Time Referenced to $\overline{\text{CAS}}$	t _{CEHWX}	t _{RCCH}	0	—	0	—	ns	13
Read Command Hold Time Referenced to $\overline{\text{RAS}}$	t _{REHWX}	t _{RRH}	0	—	0	—	ns	13
Write Command Hold Time Referenced to $\overline{\text{CAS}}$	t _{CELWH}	t _{WCH}	15	—	15	—	ns	
Write Command Hold Time Referenced to $\overline{\text{RAS}}$	t _{RELWH}	t _{WCR}	55	—	60	—	ns	
Write Command Pulse Width	t _{WLWH}	t _{WP}	15	—	15	—	ns	
Write Command to $\overline{\text{RAS}}$ Lead Time	t _{WLREH}	t _{RWL}	20	—	20	—	ns	
Write Command to $\overline{\text{CAS}}$ Lead Time	t _{WLCEH}	t _{CWL}	20	—	20	—	ns	
Data in Setup Time	t _{DVCEL}	t _{DS}	0	—	0	—	ns	14
Data in Hold Time	t _{CELDX}	t _{DH}	15	—	15	—	ns	14
Data in Hold Time Referenced to $\overline{\text{RAS}}$	t _{RELDX}	t _{DHR}	55	—	60	—	ns	
Refresh Period	t _{RVRV}	t _{RFSH}	—	8	—	8	ms	
Write Command Setup Time	t _{WLCEL}	t _{WCS}	0	—	0	—	ns	15
$\overline{\text{CAS}}$ Setup Time for $\overline{\text{CAS}}$ Before $\overline{\text{RAS}}$ Refresh	t _{RELCEL}	t _{CSR}	10	—	10	—	ns	
$\overline{\text{CAS}}$ Hold Time for $\overline{\text{CAS}}$ Before $\overline{\text{RAS}}$ Refresh	t _{RELCEH}	t _{CHR}	30	—	30	—	ns	
$\overline{\text{CAS}}$ Precharge to $\overline{\text{CAS}}$ Active Time	t _{REHCEL}	t _{RPC}	0	—	0	—	ns	
$\overline{\text{CAS}}$ Precharge Time for $\overline{\text{CAS}}$ Before $\overline{\text{RAS}}$ Counter Test	t _{CEHCEL}	t _{CPPT}	40	—	40	—	ns	
$\overline{\text{CAS}}$ Precharge Time	t _{CEHCEL}	t _{CPN}	10	—	10	—	ns	
Fast Page Mode Cycle Time	t _{CELCELP}	t _{PCP}	45	—	45	—	ns	16
Output Buffer and Turn-Off Delay	t _{CEHQZP}	t _{OFFP}	0	25	0	25	ns	10, 16
Access Time from Precharge $\overline{\text{CAS}}$	t _{CEHQVP}	t _{CPAP}	—	45	—	45	ns	10, 16

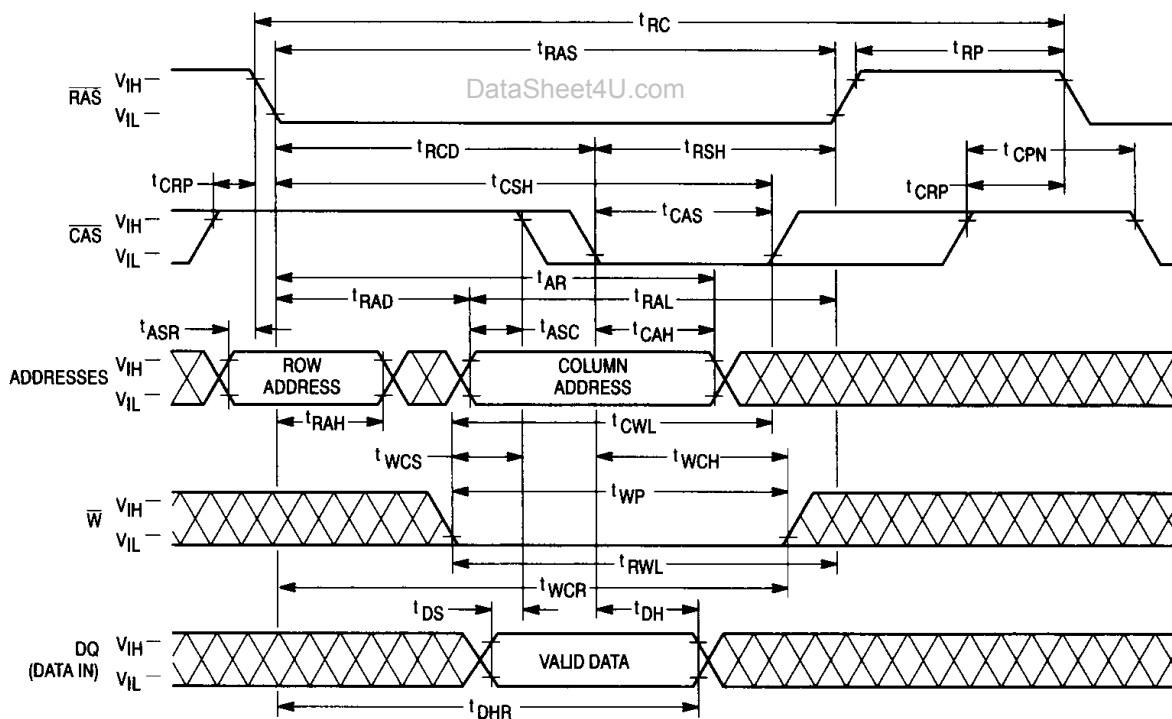
NOTES:

13. Either t_{RRH} or t_{RCCH} must be satisfied for a read cycle.
14. These parameters are referenced to $\overline{\text{CAS}}$ leading edge in early write cycles.
15. Early write only (t_{WCS} ≥ t_{WCS} (min)).
16. t_{WCS} is not a restrictive operating parameter. It is included in the data sheet as an electrical characteristic only; if t_{WCS} ≥ t_{WCS} (min), the cycle is an early write cycle and the data out pin will remain open circuit (high impedance) throughout the entire cycle. If this condition is not satisfied, the condition of the data out (at access time) is indeterminate.

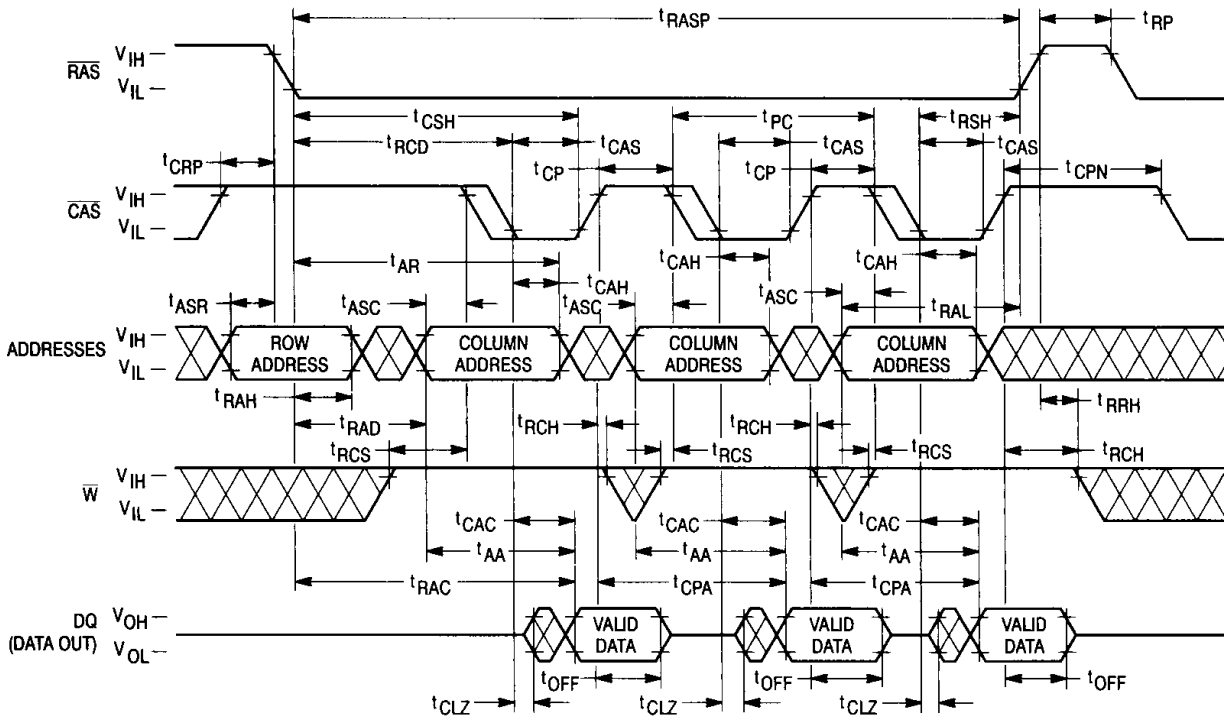
READ CYCLE



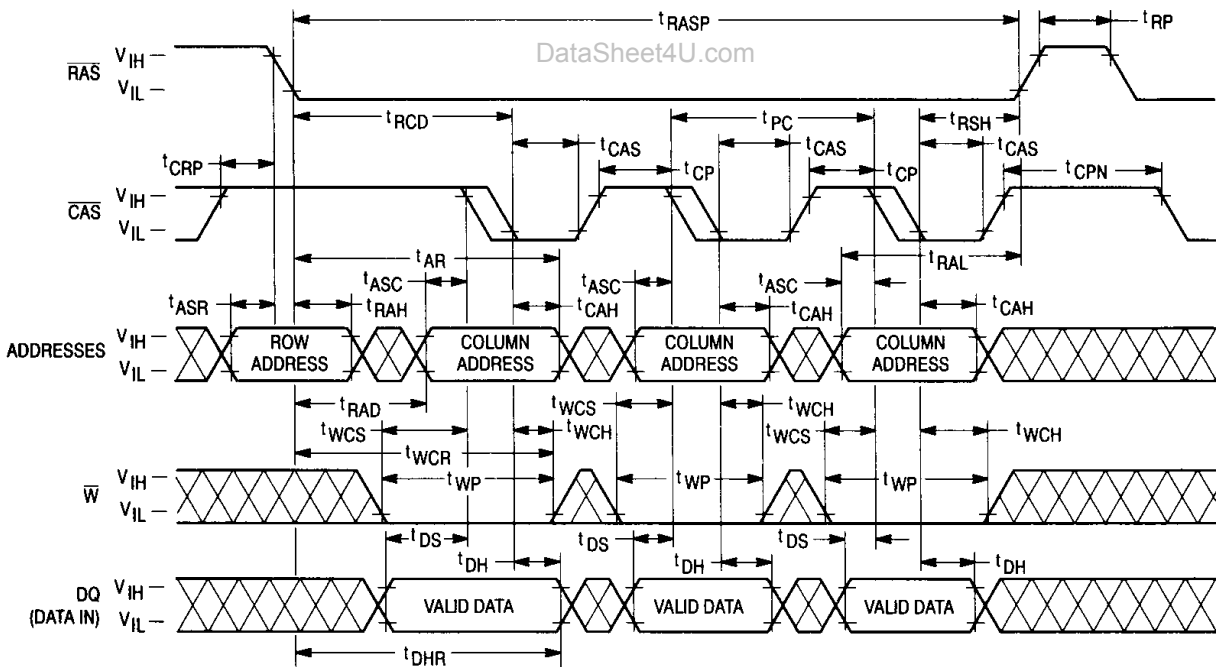
EARLY WRITE CYCLE



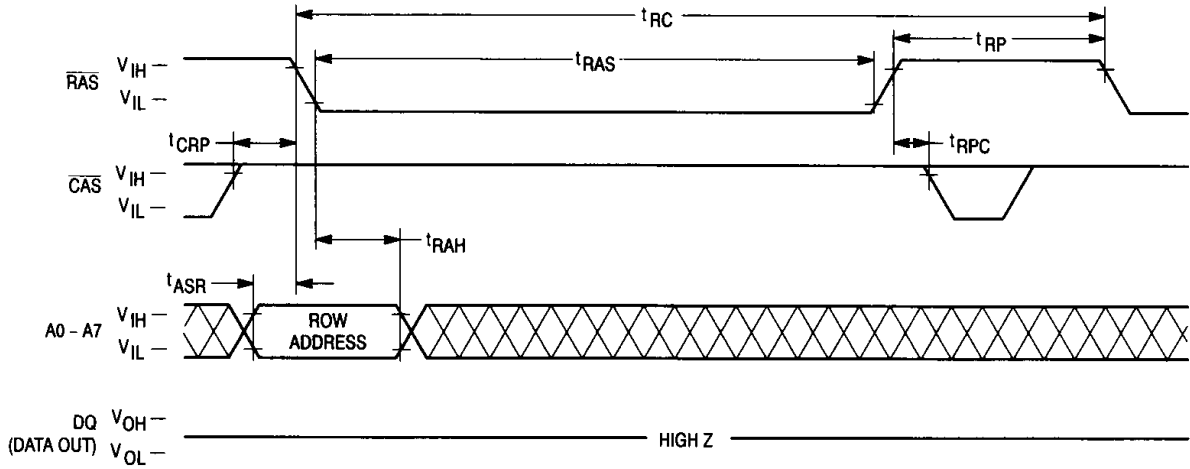
FAST PAGE MODE READ CYCLE



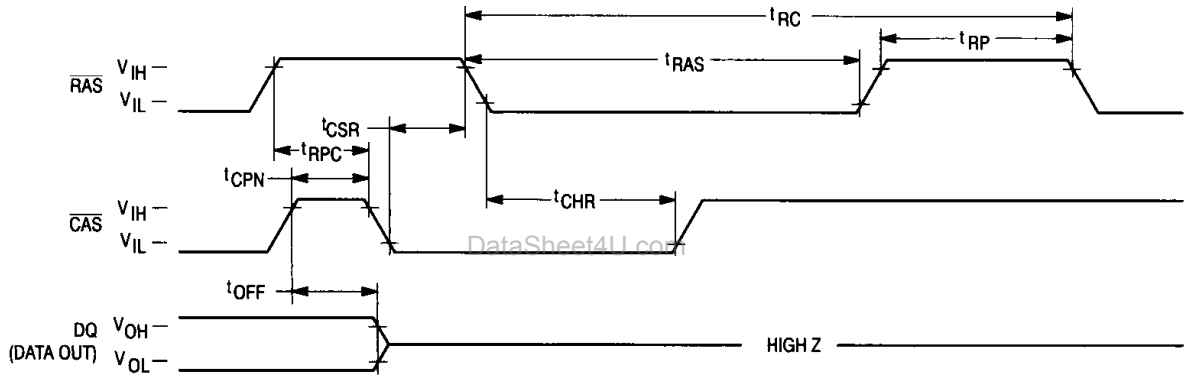
FAST PAGE MODE WRITE CYCLE (EARLY WRITE)



RAS-ONLY REFRESH CYCLE
(W and A8 are Don't Care)

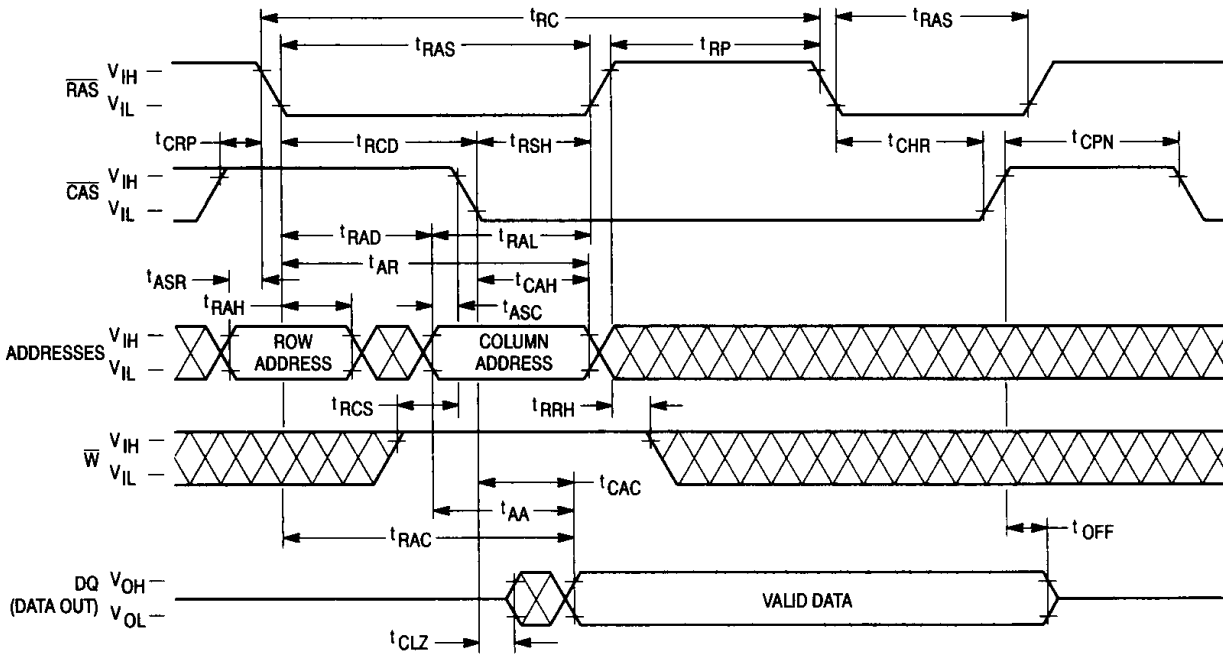


CAS BEFORE RAS REFRESH CYCLE
(W and A0 - A8 are Don't Care)



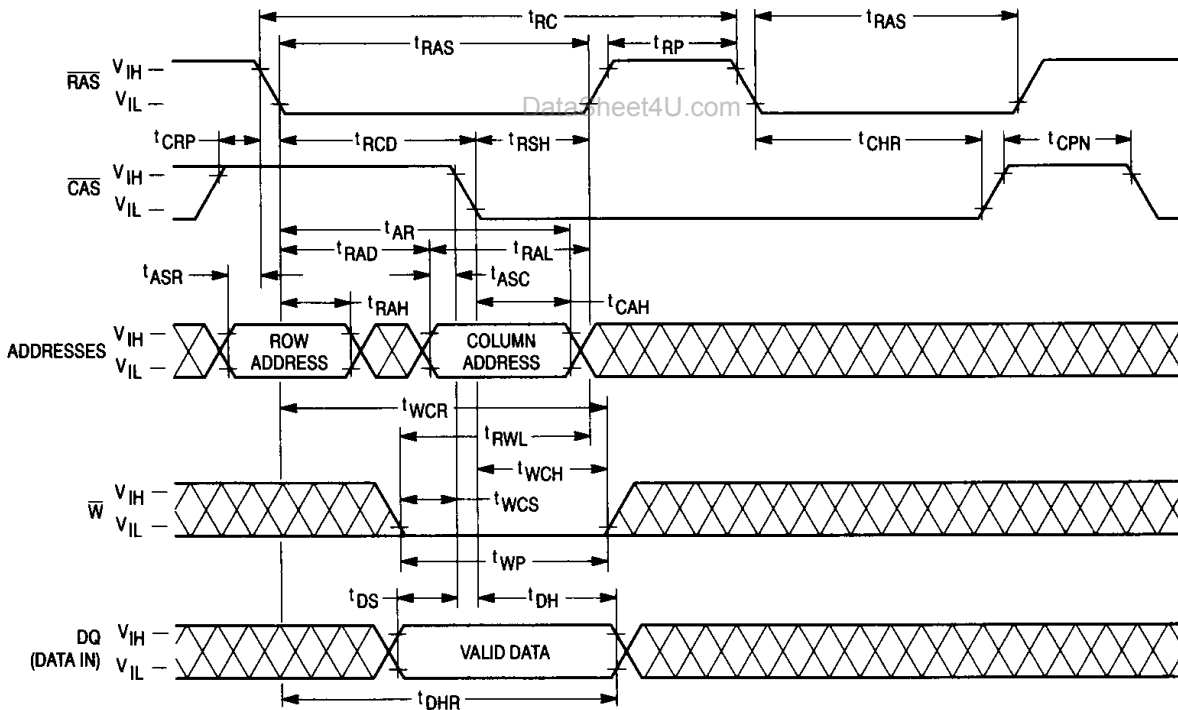
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HIDDEN REFRESH CYCLE (READ)

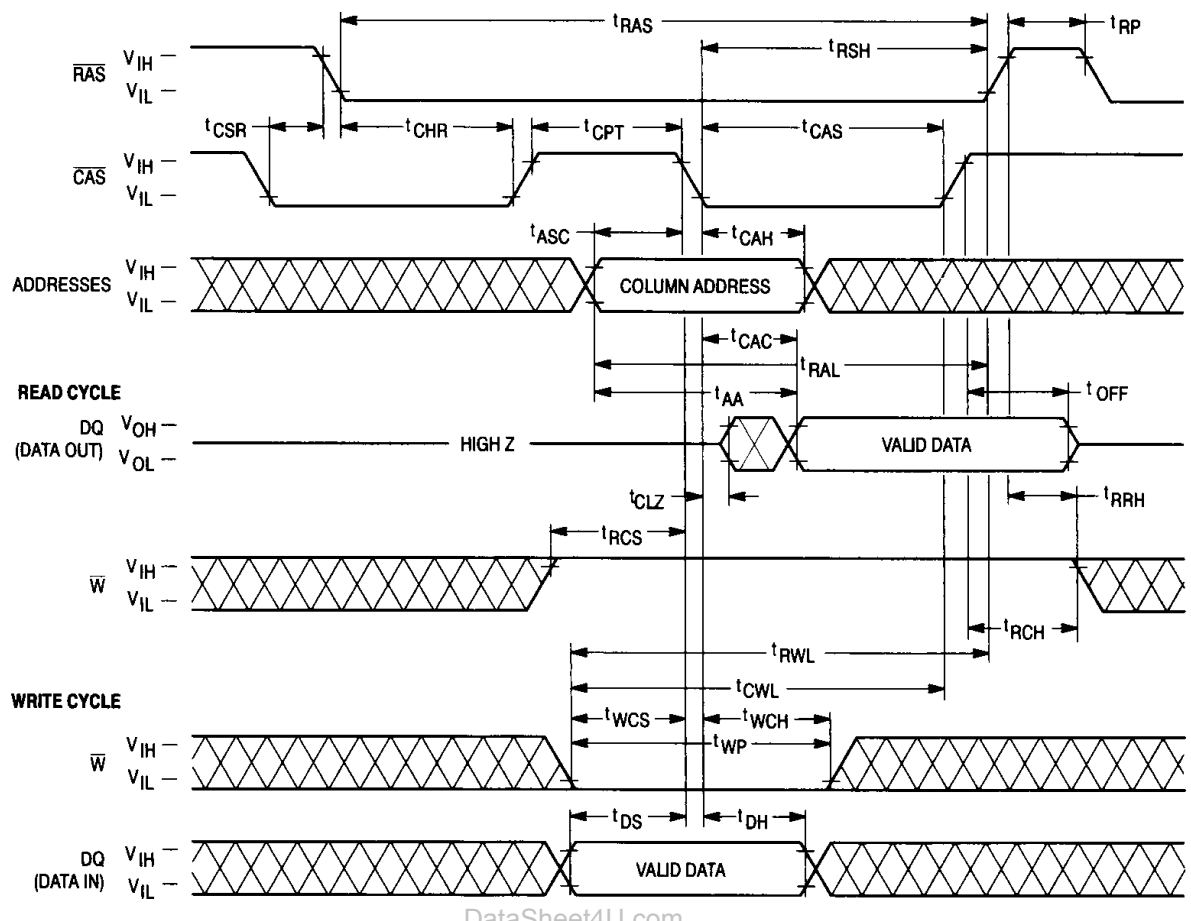


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HIDDEN REFRESH CYCLE (WRITE)



CAS BEFORE RAS REFRESH CYCLE TEST CYCLE



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DEVICE INITIALIZATION

On power-up, an initial pause of 200 microseconds is required for the internal substrate generator to establish the correct bias voltage. This must be followed by a minimum of eight active cycles of the row address strobe ($\overline{\text{RAS}}$) to initialize all dynamic nodes within the module. During an extended inactive state (greater than 8 milliseconds with the device powered up), a wake up sequence of eight active cycles is necessary to ensure proper operation.

ADDRESSING THE RAM

The nine address pins on the device are time multiplexed at the beginning of a memory cycle by two clocks, row address strobe ($\overline{\text{RAS}}$) and column address strobe ($\overline{\text{CAS}}$), into two separate 9-bit address fields. A total of eighteen address bits, nine rows and nine columns, will decode one of the 262,144 word locations in the device. $\overline{\text{RAS}}$ active transition is followed by $\overline{\text{CAS}}$ active transition (active = V_{IL} , t_{RCD} minimum) for all read or write cycles. The delay between $\overline{\text{RAS}}$ and $\overline{\text{CAS}}$ active transitions, referred to as the **multiplex window**, gives a system designer flexibility in setting up the external addresses into the RAM.

The external $\overline{\text{CAS}}$ signal is ignored until an internal $\overline{\text{RAS}}$ signal is available. This gate feature on the external $\overline{\text{CAS}}$ clock enables the internal $\overline{\text{CAS}}$ line as soon as the row address hold time (t_{RAH}) specification is met (and defines t_{RCD} minimum). The multiplex window can be used to absorb skew delays in switching the address bus from row to column addresses and in generating the $\overline{\text{CAS}}$ clock.

There are two other variations in addressing the module: **RAS-only refresh cycle** and **CAS before RAS refresh cycle**. Both are discussed in separate sections that follow.

READ CYCLE

The DRAM may be read with either a normal random read cycle or a page mode read cycle. The normal read cycle is outlined here, while the page mode cycle is discussed in a separate section.

The normal read cycle begins as described in **ADDRESSING THE RAM**, with $\overline{\text{RAS}}$ and $\overline{\text{CAS}}$ active transitions latching the desired bit location. The write ($\overline{\text{W}}$) input level must be high (V_{IH}), t_{RCS} (minimum) before the $\overline{\text{CAS}}$ active transition, to enable read mode.

Both the $\overline{\text{RAS}}$ and $\overline{\text{CAS}}$ clocks trigger a sequence of events that are controlled by several delayed internal clocks. The internal clocks are linked in such a manner that the read access time of the device is independent of the address multiplex window. $\overline{\text{CAS}}$ controls read access time; $\overline{\text{CAS}}$ must be active before or at t_{RCD} maximum to guarantee valid data out (DQ) at t_{RAC} (access time from $\overline{\text{RAS}}$ active transition). If the t_{RCD} maximum is exceeded, read access time is determined by the $\overline{\text{CAS}}$ active transition (t_{CAC}).

The $\overline{\text{RAS}}$ and $\overline{\text{CAS}}$ clocks must remain active for minimum times of t_{RAS} and t_{CAS} , respectively, to complete the read cycle. $\overline{\text{W}}$ must remain high throughout the cycle, and for time t_{RRH} or t_{RCH} after $\overline{\text{RAS}}$ or $\overline{\text{CAS}}$ inactive transition, respectively, to maintain the data at that bit location. Once $\overline{\text{RAS}}$ transitions to inactive, it must remain inactive for a minimum time of t_{RP} to precharge the internal device circuitry for the next active cycle. DQ is valid, but not latched, as long as the $\overline{\text{CAS}}$ clock is active. When the $\overline{\text{CAS}}$ clock transitions to

inactive, the output will switch to High Z, t_{OFF} after inactive transition.

WRITE CYCLE

The DRAM may be written with either an early write or page mode early write cycle. The early write mode is discussed here, while the page mode write operation is covered in another section.

A write cycle begins as described in **ADDRESSING THE RAM**. Write mode is enabled by the transition of $\overline{\text{W}}$ to active (V_{IL}). Early write mode is distinguished by the active transition of $\overline{\text{W}}$, with respect to $\overline{\text{CAS}}$. Minimum active time t_{RAS} and t_{CAS} , and precharge time t_{RP} apply to write mode, as in the read mode.

An early write cycle is characterized by $\overline{\text{W}}$ active transition at minimum time t_{WCS} before $\overline{\text{CAS}}$ active transition. Data In (DQ) is referenced to $\overline{\text{CAS}}$ in an early write cycle. $\overline{\text{RAS}}$ and $\overline{\text{CAS}}$ clocks must stay active for t_{RWL} and t_{CWL} , respectively, after the start of the early write operation to complete the cycle.

PAGE MODE CYCLES

Page mode allows fast successive data operations at all 512 column locations on a selected row of the module. Read access time in page mode (t_{CAC}) is typically half the regular $\overline{\text{RAS}}$ clock access time (t_{RAC}). Page mode operation consists of keeping $\overline{\text{RAS}}$ active while toggling $\overline{\text{CAS}}$ between V_{IH} and V_{IL} . The row is latched by $\overline{\text{RAS}}$ active transition, while each $\overline{\text{CAS}}$ active transition allows selection of a new column location on the row.

A page mode cycle is initiated by a normal read or write cycle, as described in prior sections. Once the timing requirements for the first cycle are met, $\overline{\text{CAS}}$ transitions to inactive for minimum t_{CP} , while $\overline{\text{RAS}}$ remains low (V_{IL}). The second $\overline{\text{CAS}}$ active transition while $\overline{\text{RAS}}$ is low initiates the first page mode cycle (t_{PC}). Either a read or write operation can be performed in a page mode cycle, subject to the same conditions as in normal operation (previously described). These operations can be intermixed in consecutive page mode cycles and performed in any order. The maximum number of consecutive page mode cycles is limited by t_{RASP} . Page mode operation is ended when $\overline{\text{RAS}}$ transitions to inactive, coincident with or following $\overline{\text{CAS}}$ inactive transition.

REFRESH CYCLES

The dynamic RAM design is based on capacitor charge storage for each bit in the array. This charge degrades with time and temperature, thus each bit must be periodically refreshed (recharged) to maintain the correct bit state. Bits in the MCM94256 require refresh every 8 milliseconds.

Refresh is accomplished by cycling through the 512 row addresses in sequence within the specified refresh time. All the bits on a row are refreshed simultaneously when the row is addressed. Distributed refresh implies a row refresh every 15.6 microseconds for the MCM94256. Burst refresh, a refresh of all 512 rows consecutively, must be performed every 8 milliseconds on the MCM94256A.

A normal read or write operation to the RAM will refresh all the bits associated with the particular row decoded. Three other methods of refresh, **RAS-only refresh**, **CAS before RAS refresh**, and **hidden refresh** are available on this device for greater system flexibility.

RAS-Only Refresh

$\overline{\text{RAS}}$ -only refresh consists of $\overline{\text{RAS}}$ transition to active, latching the row address to be refreshed, while $\overline{\text{CAS}}$ remains high (V_{IH}) throughout the cycle. An external counter is employed to ensure that all rows are refreshed within the specified limit.

CAS Before RAS Refresh

$\overline{\text{CAS}}$ before $\overline{\text{RAS}}$ refresh is enabled by bringing $\overline{\text{CAS}}$ active before $\overline{\text{RAS}}$. This clock order activates an internal refresh counter that generates the row address to be refreshed. External address lines are ignored during the automatic refresh cycle. The output buffer remains at the same state it was in during the previous cycle (hidden refresh).

Hidden Refresh

Hidden refresh allows refresh cycles to occur while maintaining valid data at the output pin. Holding $\overline{\text{CAS}}$ active at the end of a read or write cycle, while $\overline{\text{RAS}}$ cycles inactive for t_{RP} and back to active, starts the hidden refresh. This is essentially the execution of a $\overline{\text{CAS}}$ before $\overline{\text{RAS}}$ refresh from a cycle in progress (see Figure 1).

CAS BEFORE RAS REFRESH COUNTER TEST

The internal refresh counter of this device can be tested with a **CAS before RAS refresh counter test**. This refresh counter test is performed with read and write operations. During this test, the internal refresh counter generates the row address, while the external address input supplies the column address. The entire array is refreshed after 512 test cycles, as indicated by the check data written in each row. See **CAS before RAS refresh counter test cycle** timing diagram.

The test can be performed only after a minimum of 8 **CAS before RAS** initialization cycles. The test procedure is as follows:

1. Write "0"s into all memory cells (normal write mode).
2. Select a column address, and read "0" out of the cell by performing **CAS before RAS refresh counter test, read cycle**. Repeat this operation 512 times.
3. Select a column address, and write "1" into the cell by performing the **CAS before RAS refresh counter test, write cycle**. Repeat this operation 512 times.
4. Read "1"s (normal read mode), which were written at step 3.
5. Repeat steps 1 to 4 using complement data.

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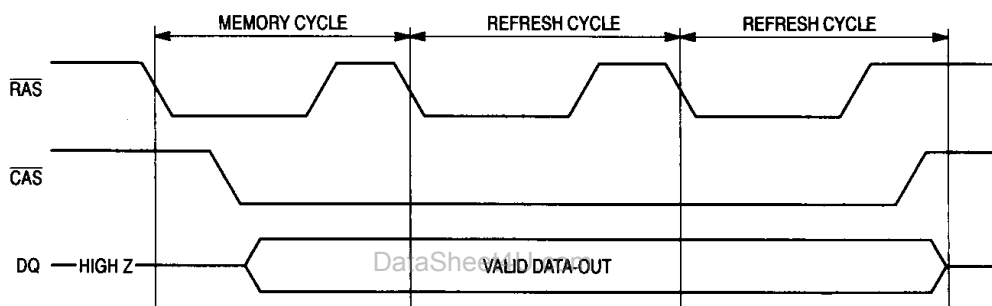


Figure 1. Hidden Refresh Cycle

ORDERING INFORMATION
(Order by Full Part Number)

	MCM	94256	X	XX	
Motorola Memory Prefix	_____	_____	_____	_____	Speed (70 = 70 ns, 80 = 80 ns)
Part Number	_____	_____	_____	_____	Package (S = SIMM)

Full Part Numbers — MCM94256S70
MCM94256S80

NOTE: For mechanical data, please see Chapter 10.

MCM94256
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MOTOROLA DRAM DATA